



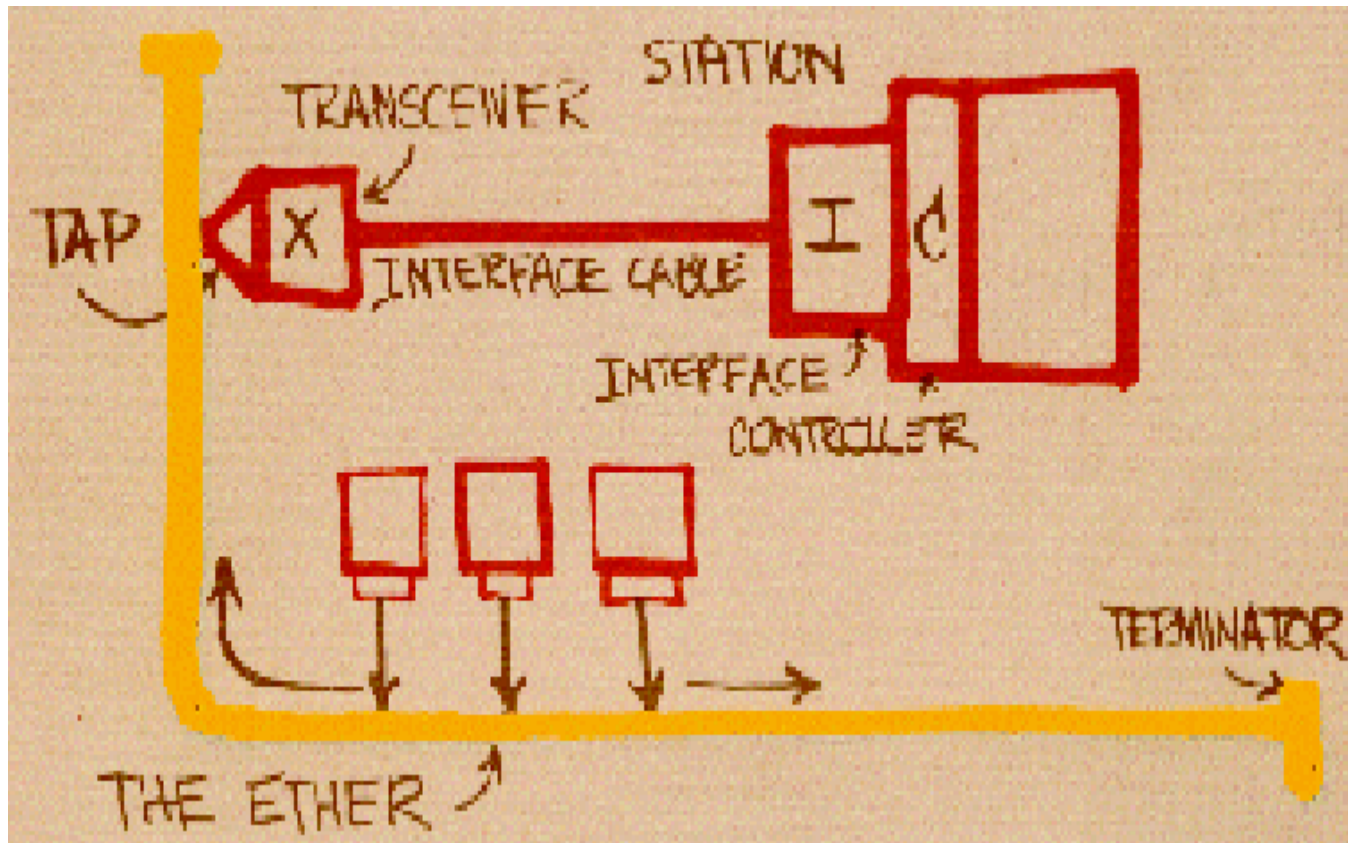
Standardization of Industrial Ethernet – the next battlefield?

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Ethernet is more than 30 years of history...



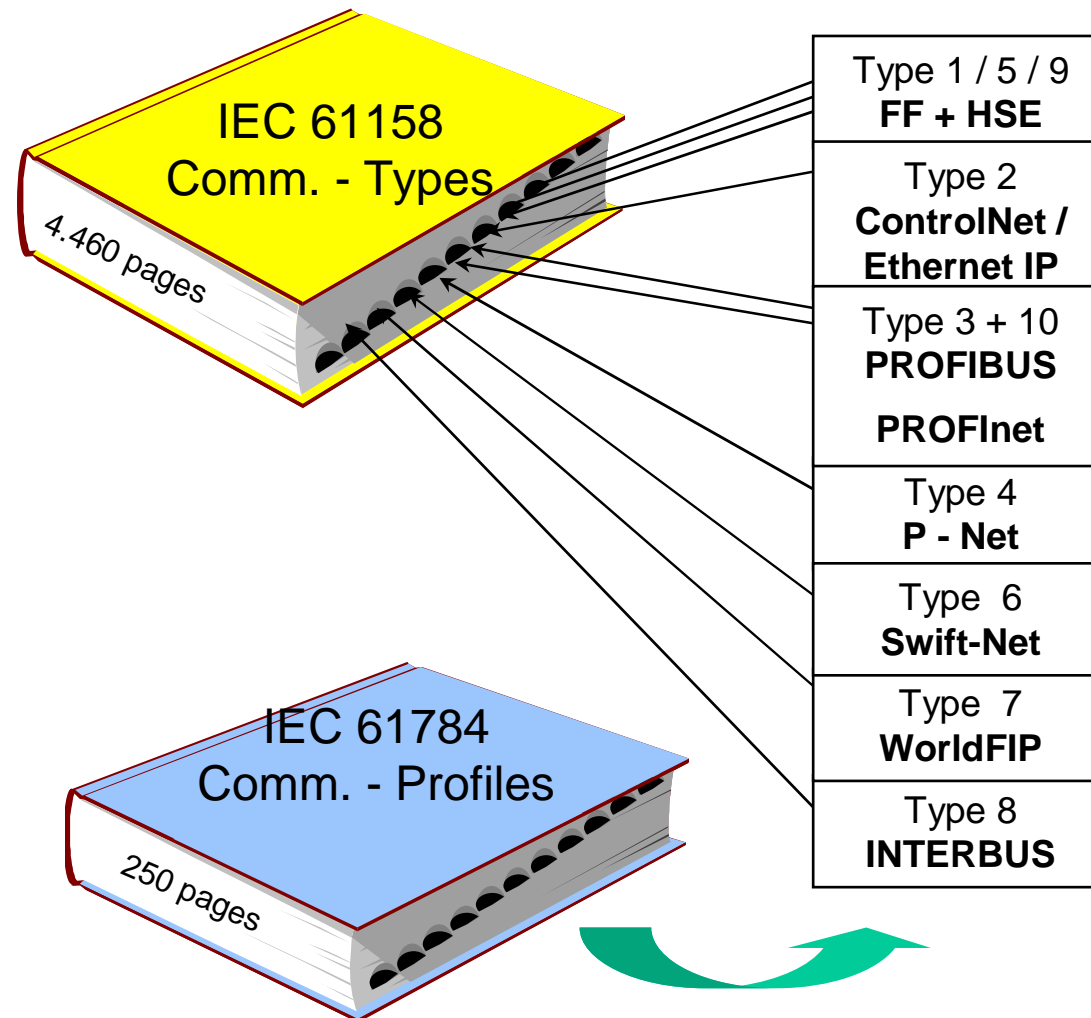
Designed by Bob Metcalf at PARC in 1972/ 3



Why Ethernet in automation?

- Ethernet is already the office world standard
- Ethernet is already used for higher level communications in the automation world
- Ethernet may also be used for communication between controllers and field devices
- IT functionality could also be applicable to automation applications
- **Advantage:**
 - Vertical integration of field communications with Manufacturing Execution Systems (MES)
- **Challenge:**
 - Protect existing fieldbus investment
 - Bring real time functionality to Ethernet

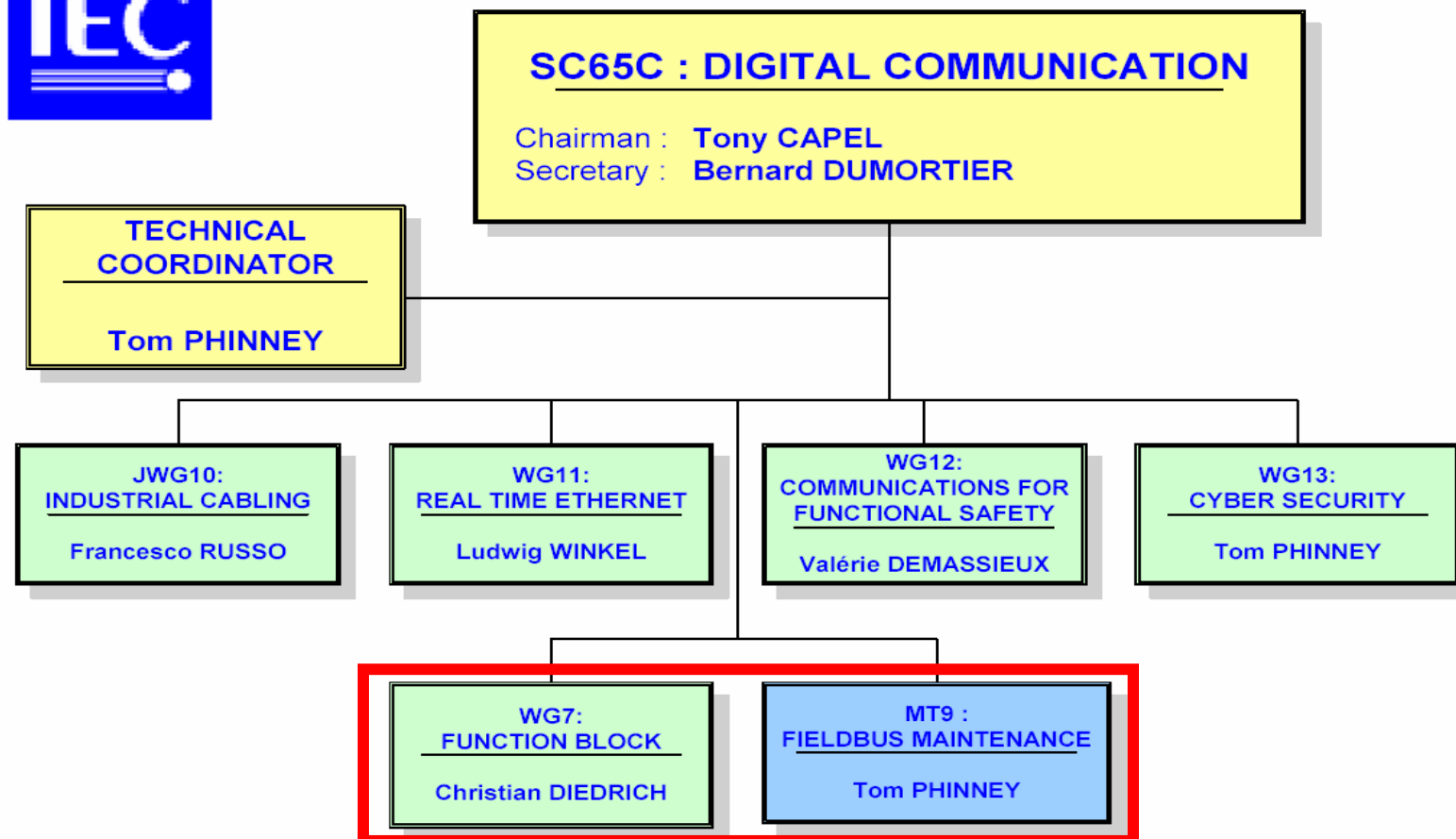
The international fieldbus - IEC 61158



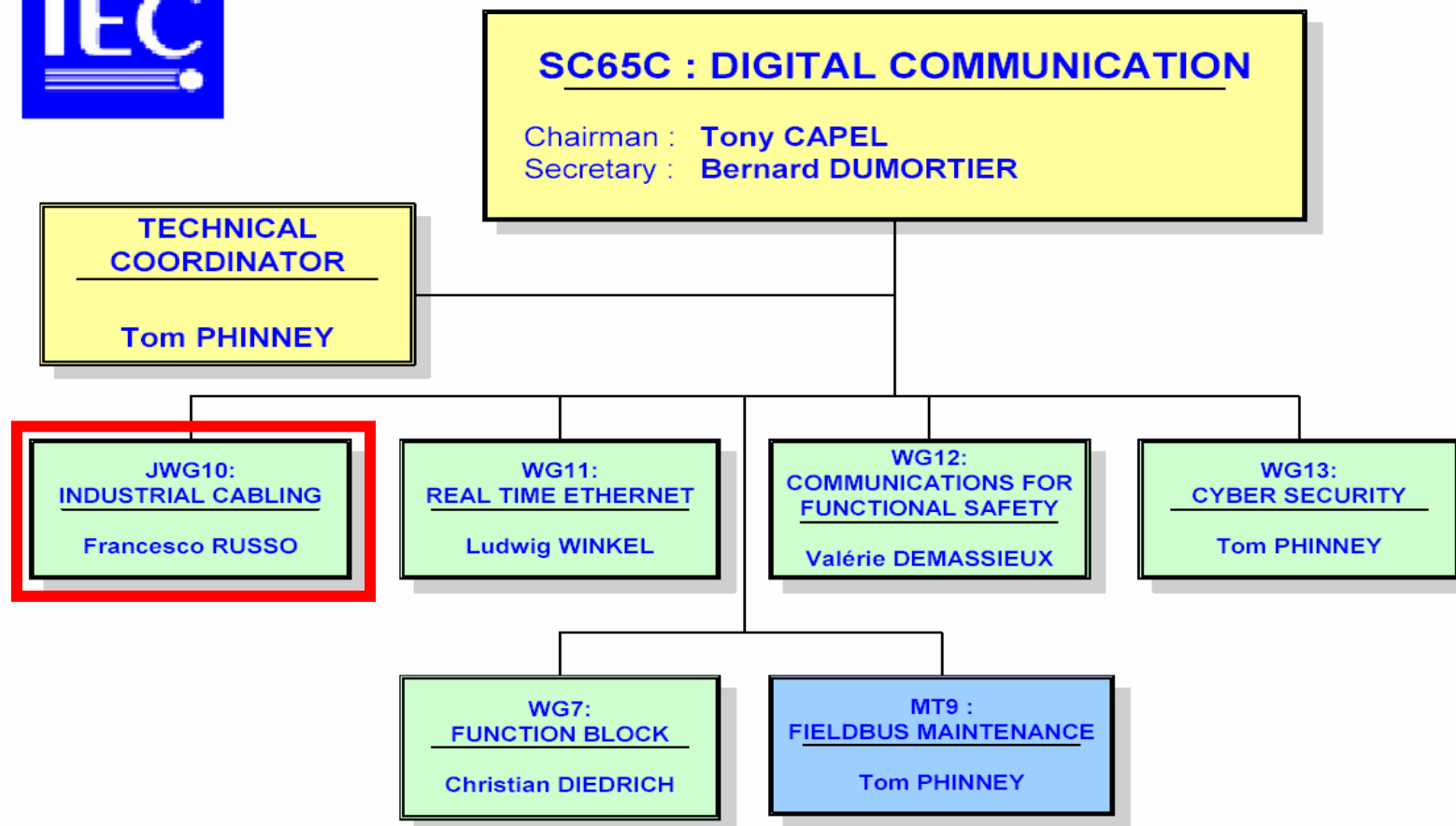
The international fieldbus – IEC 61784-1

CPF1 (FOUNDATION® Fieldbus)	CP 1/1	H1
	CP 1/2	HSE
	CP 1/3	H2
CPF2 (ControlNet™)	CP 2/1	ControlNet
	CP 2/2	EtherNet/IP
CPF3 (PROFIBUS)	CP 3/1	PROFIBUS DP
	CP 3/2	PROFIBUS PA
	CP 3/3	PROFINet
CPF4 (P-NET®)	CP 4/1	P-NET RS-485
	CP 4/2	P-NET RS-232
CPF5 (WorldFIP®)	CP 5/1	WorldFIP
	CP 5/2	WorldFIP with subMMS
	CP 5/3	WorldFIP minimal for TCP/IP
CPF6 (INTERBUS®)	CP 6/1	INTERBUS
	CP 6/2	INTERBUS TCP/IP
	CP 6/3	INTERBUS minimal [subset of CP
CPF7 (SwiftNet)	CP 7/1	SwiftNet Transport
	CP 7/2	SwiftNet Full stack

New structure of IEC65C for Industrial Ethernet

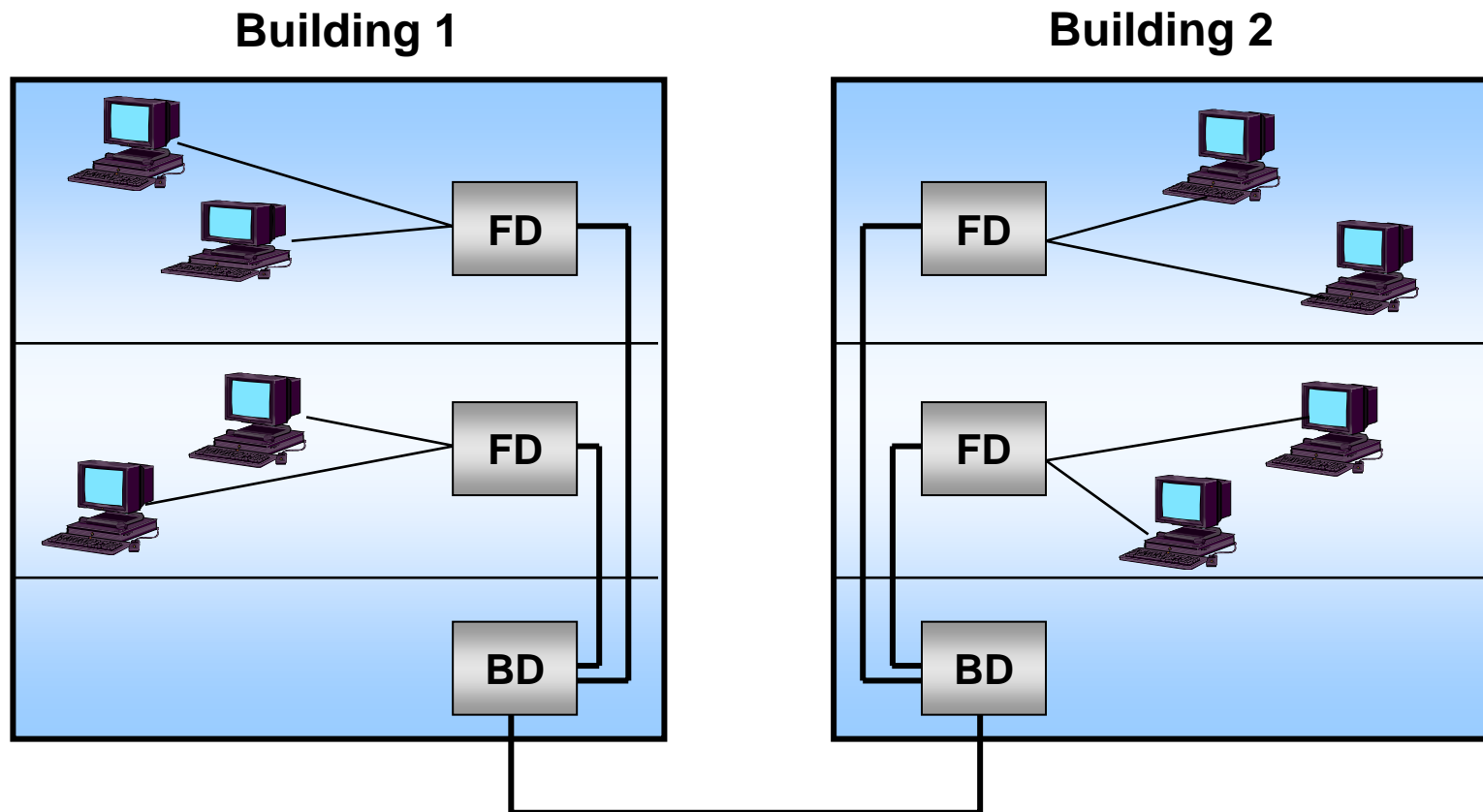


New structure of IEC65C for Industrial Ethernet



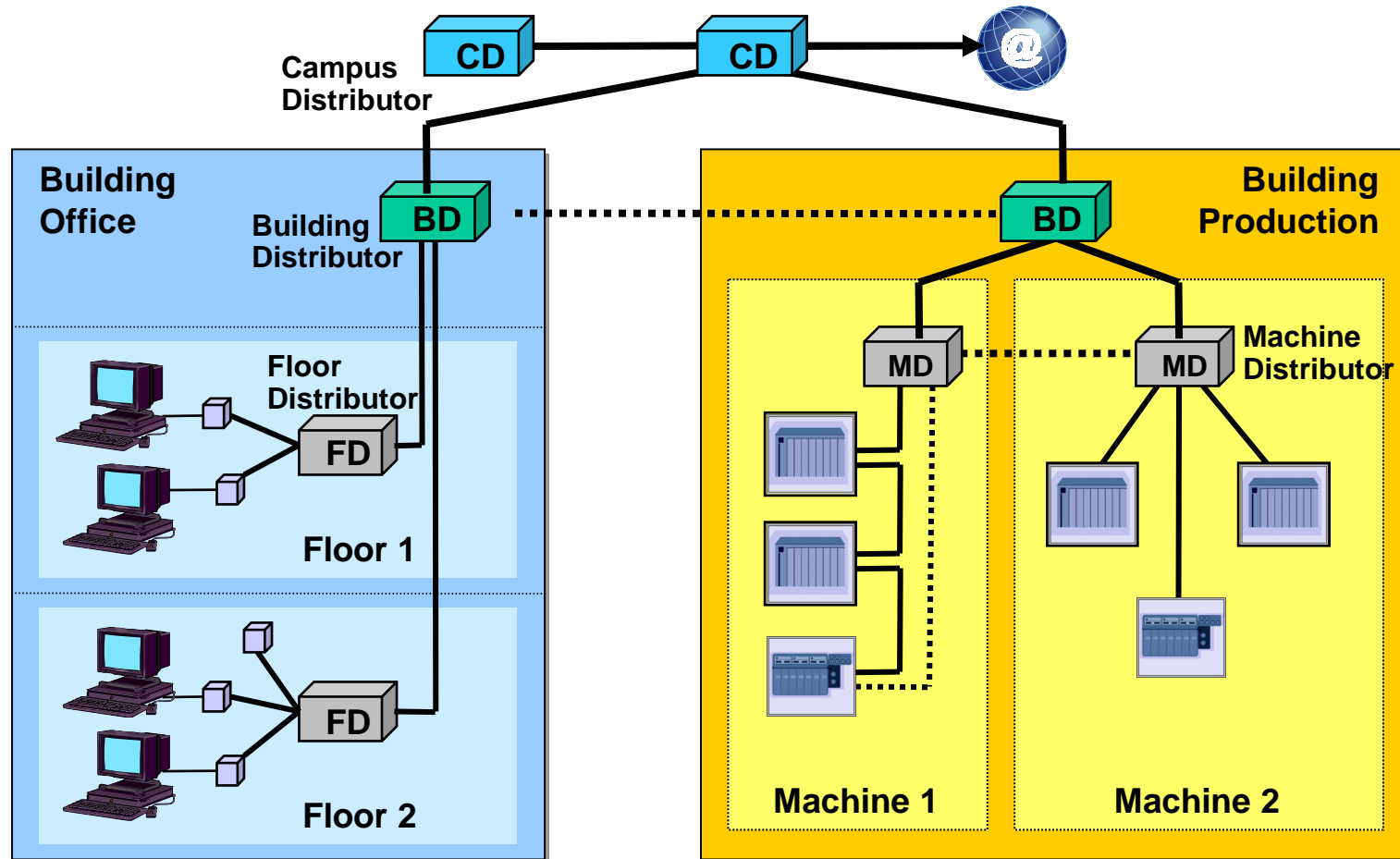
Ethernet Networks in Office Area

⇒ Tree structured net topologies following ISO/IEC 11801 with application independent cabling systems



BD = Building Distributor, FD = Floor Distributor

Ethernet Networks in Industrial Area



⇒ fixed basic installation with variable device connections

⇒ Plant specific cabling with individual net structure

⇒ Star and tree structures

⇒ Star, ring and line structures

Differences between Office and Industry

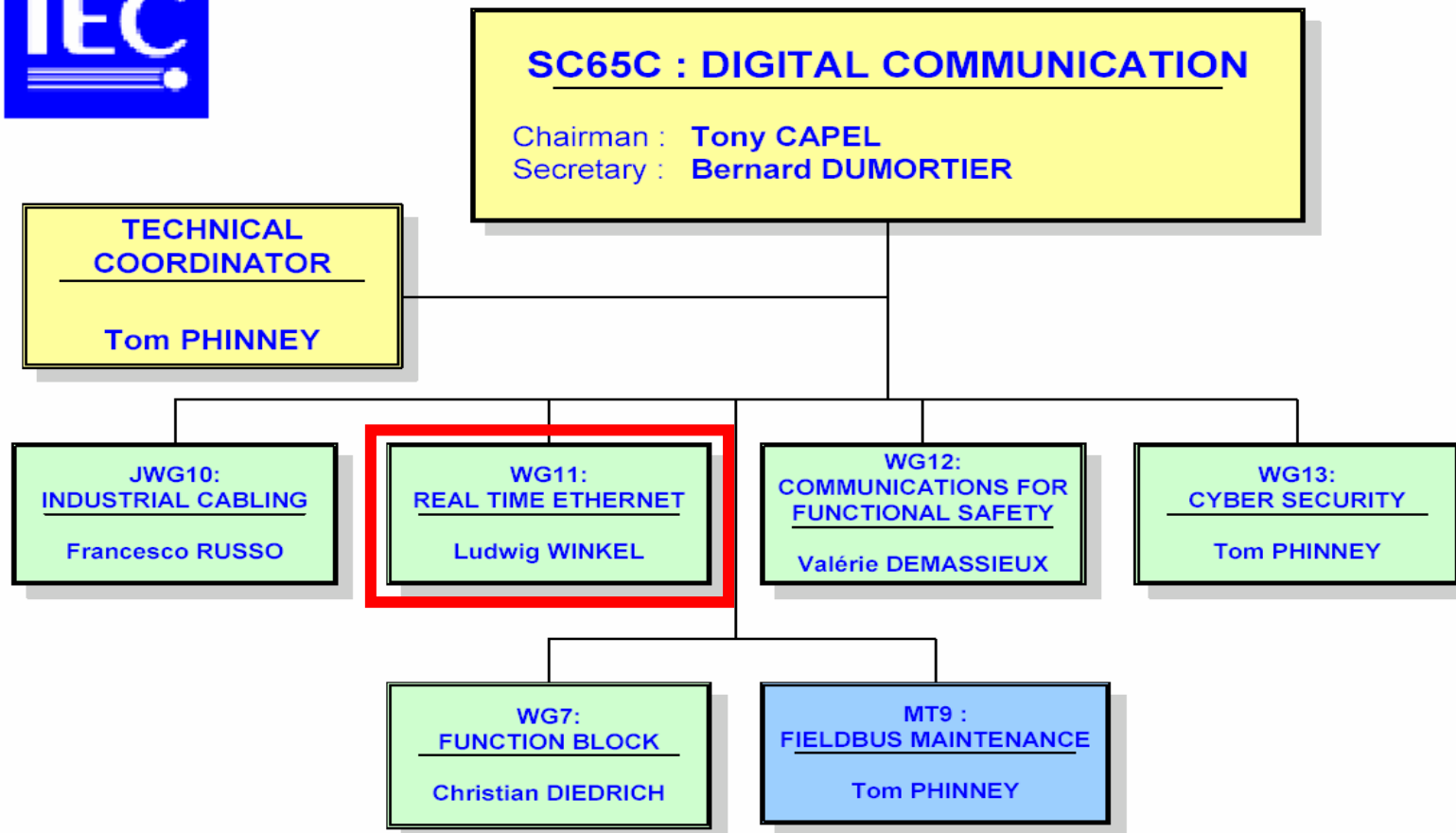
⇒ Office Area	⇒ Production Area
⇒ Fixed basic installation in a building	⇒ Largely system-related cabling
⇒ Laid under raised floors	⇒ System-related cable routing
⇒ Variable device connection at workplace	⇒ Connection points are seldom changed
⇒ Pre-fabricated device connection cable	⇒ Field-preparable device connections
⇒ Tree-shape network structures	⇒ Quite often: line-form network structures and (redundant) ring structures
⇒ Large data packets (e.g. images)	⇒ Small data packets (measured values)
⇒ Medium network availability	⇒ Very high network availability
⇒ Moderate temperatures (from 0 to 50°C)	⇒ Extreme temperatures (from -20 to +70°C)
⇒ No moisture	⇒ Moisture possible (IP65)
⇒ Virtually no vibrations	⇒ Vibrating machines
⇒ Low EMC burden	⇒ High EMC burden
⇒ Low mechanical danger	⇒ Danger of mechanical damage
⇒ Virtually no chemical danger	⇒ Chemical burden from oily or aggressive atmospheres



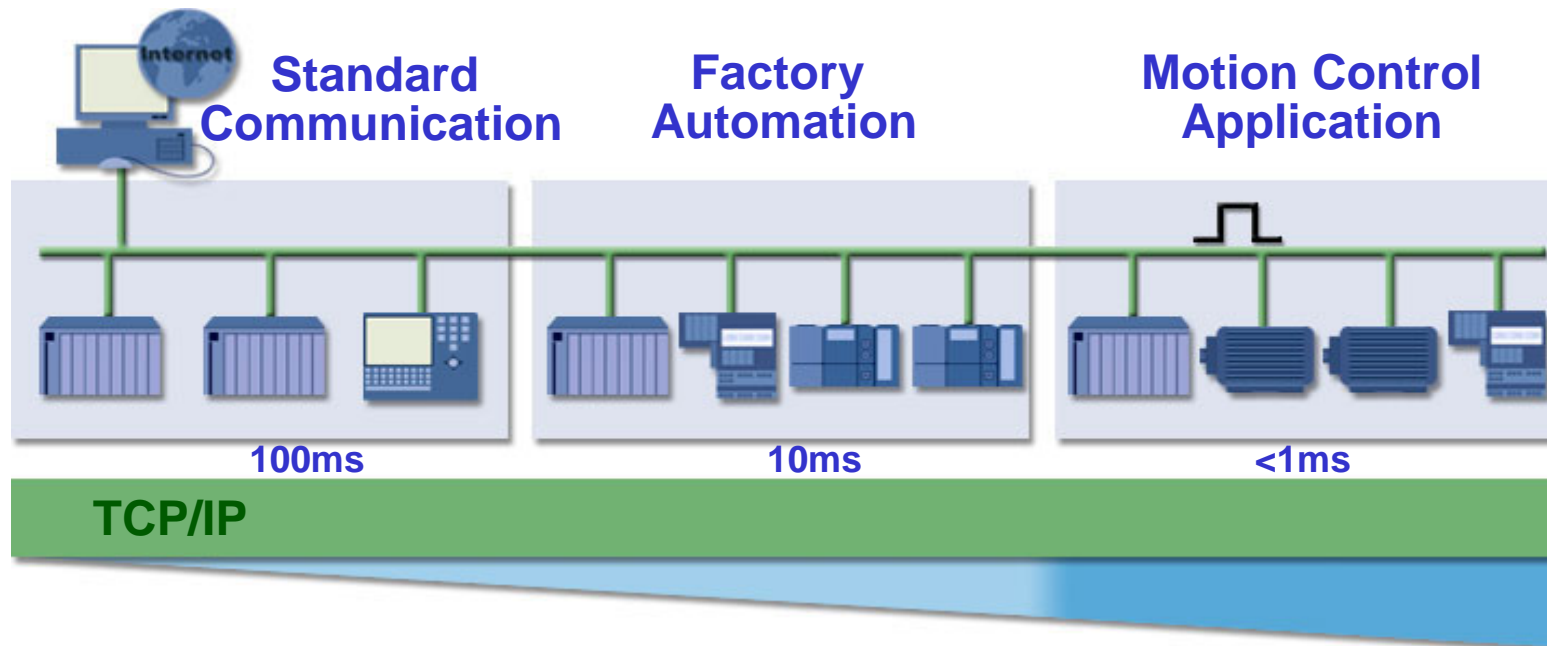
Sealed RJ45 connectors



New structure of IEC65C for Industrial Ethernet

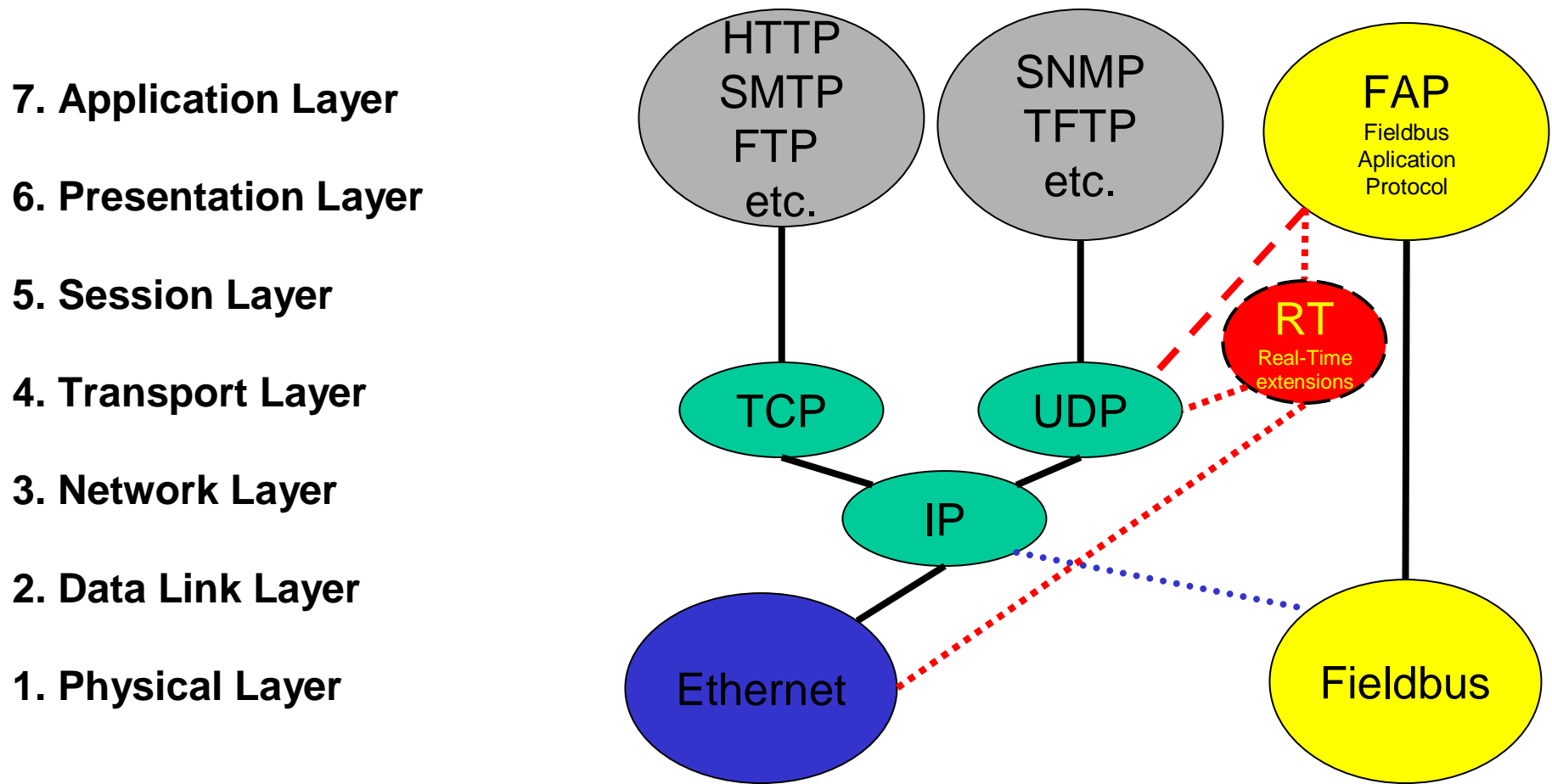


Real-time requirements for Automation



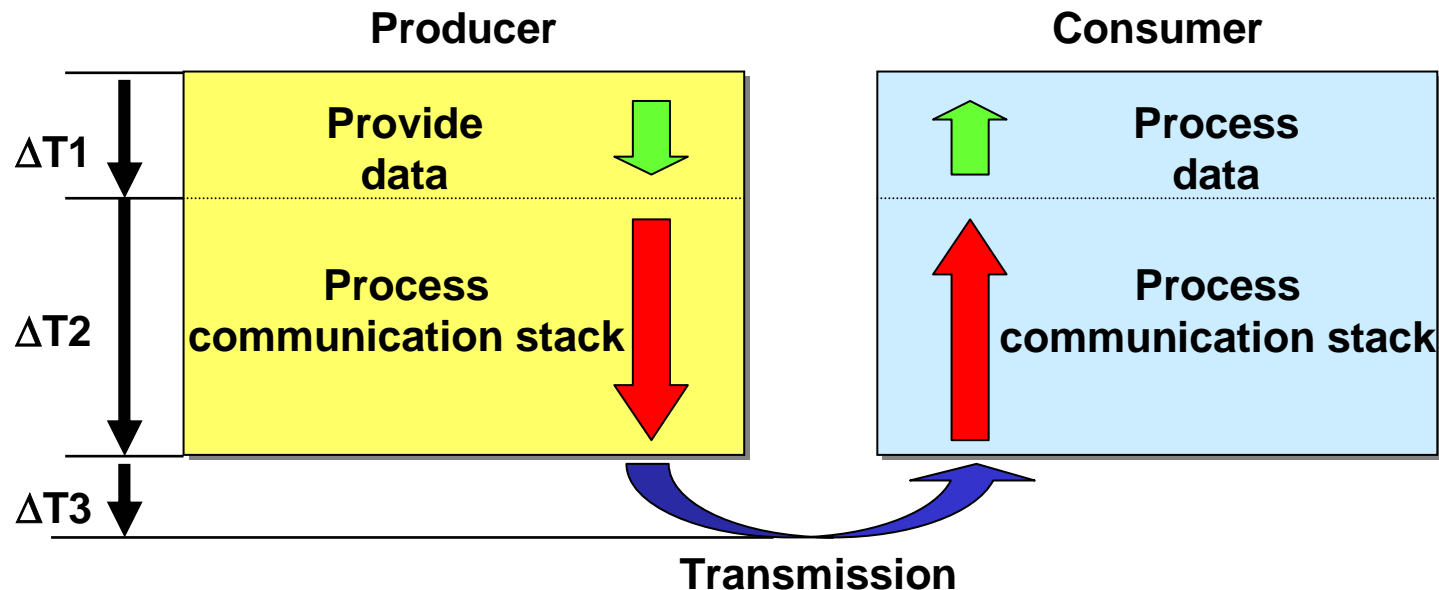
- Coexistent use of real-time and IT communication on one line
- Uniform real-time protocol for all requirements
- Scalable real-time communication from high-performance to isochronous

Possible structures of Industrial Ethernet

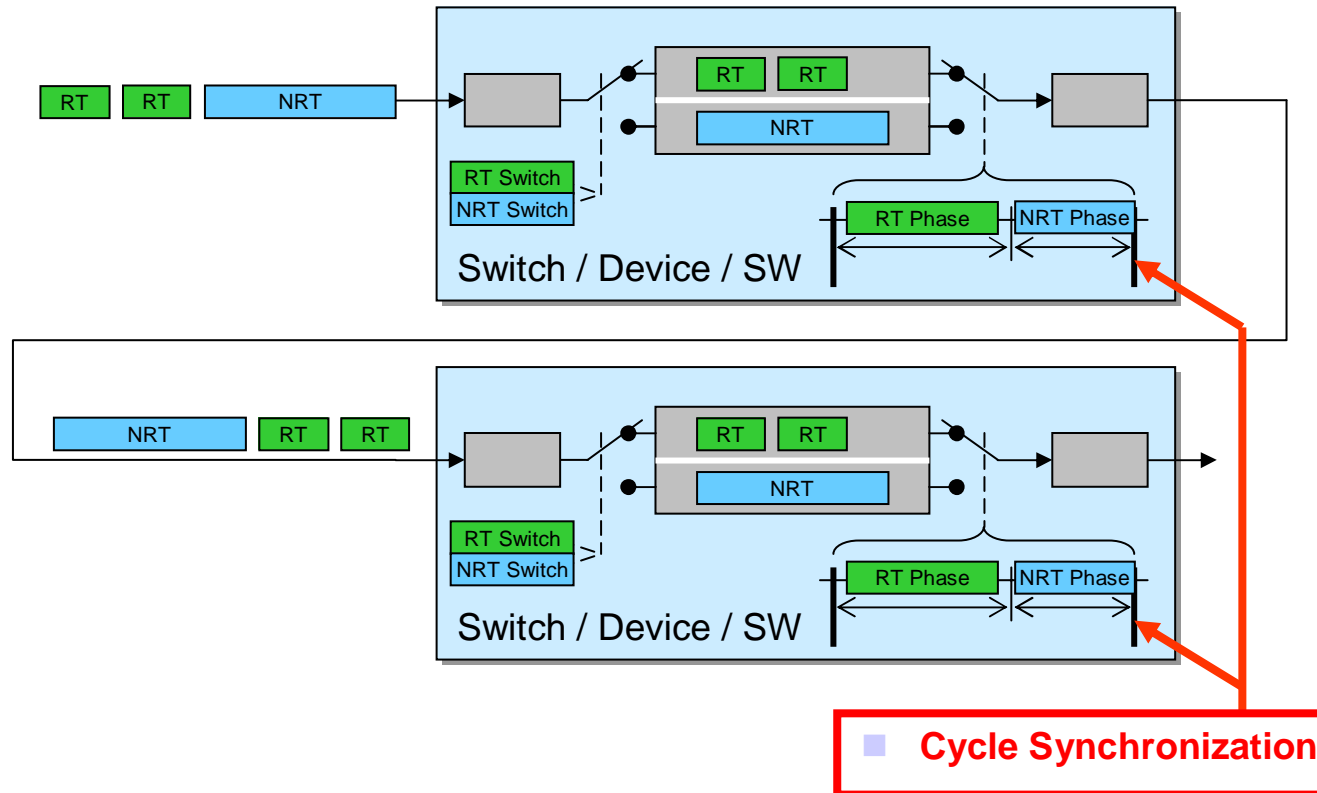


Improving Performance in the Communication Stack

- ⇒ The time needed for the provision and processing of the data is independent of communication
- ⇒ Improved performance is possible through optimization of the turnaround times in the communication stack
- ⇒ Reaction time less than 1 ms only if access method is modified
- ⇒ Three solutions:
 - ✓ **Best effort** / **Reduced communication stack** / **Modified access method**



General Behavior of Realtime Ethernet



Realtime data is transmitted in different timeslots than non realtime data

- ✓ The differentiation is done in the switching hardware
- ✓ The differentiation is done in the device hardware
- ✓ The differentiation is done in the device software



Rules for IEC 61784-2

The classification of a RTE communication network shall be described within the technology specific subclauses using:

- ⇒ a class specific list of indicators – optionally with their limits or ranges – to show the capabilities of a CP
- ⇒ a set of lists with consistent indicators of the capabilities. Each of the tables has one indicator as a leading constant and showing the related limits of the indicators.
- ⇒ an optional graphical representation of the typical ranges of values and the associated equations.



RTE performance indicators (1)

Delivery Time

- ⇒ **Delivery time is the time needed to convey a SDU (message payload) from one node (source) to another node (destination). The delivery time is measured at the Application Layer SAP interface.**
- ⇒ **The maximum delivery time shall be stated for two cases:**
 - ⇒ • **no transmission errors and**
 - ⇒ • **one lost frame with recovery**



RTE performance indicators (2)

Number of end nodes

- ⇒ **Number of end nodes states the maximum number of RTE end devices supported by a CP.**
 - ✓ The network devices like a switch are not counted in the number of nodes.

Basic network topology

- ⇒ **The basic network topology supported by a CP is stated out of the topologies listed in Table 9, or as a combination.**

Number of switches between end nodes

- ⇒ **Number of switches between end nodes supported by a CP.**

Basic network topology	CP
hierarchical star	CP m/1
loop (ring)	CP m/2
daisy-chain	CP m/3
NOTE A real topology could be any combination of the three basic topologies.	



RTE performance indicators (3)

Throughput RTE

⇒ Throughput RTE is the total amount of APO data (by octet length) on one link received on related AREPs through the path per second.

(Throughput non-RTE)

⇒ Throughput non-RTE is the transmission capacity for non-RTE communication in bps.

⇒ Throughput non-RTE is the percentage of bandwidth, which can be used for Non-RTE communication.



RTE performance indicators (4)

Time synchronization accuracy

⇒ Time synchronization accuracy shall indicate the maximum deviation between any two node clocks.

Redundancy recovery times

⇒ Redundancy recovery time shall indicate the high limit maximum recovery time in case of a single permanent failure.

- ✓ Delivery Time with permanent failures, but not with transient failures is replaced in that case by the recovery time.

Example of conformance statement

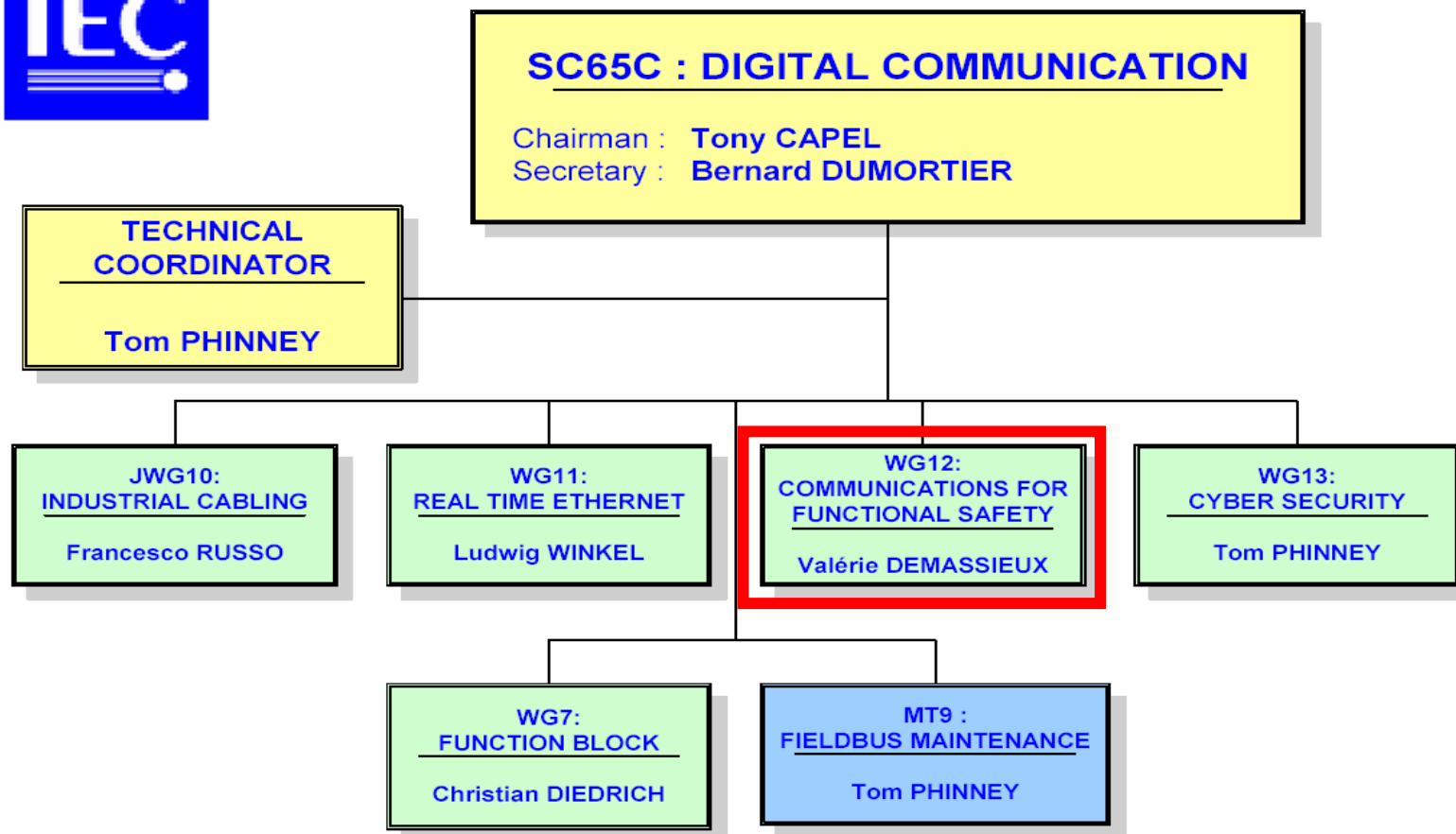
Indicators	CP 2/3	CP 2/4	CP 2/5
Delivery time less then [ms]	4	1	0,25
Nodes more then [number of bridges in-between nodes]	a) 1-200, see 7.1.1 b) 1- 20 nodes in a star or c) less then 10 bridges in between nodes	50 nodes in a star or less then 10 bridges in-between nodes	250 nodes in a star or less then 10 bridges in-between nodes
Throughput RTE (90%); more then [std.-messages]	20.000	20.000	20.000
Throughput Non-RTE (90%); more then [Mbit/s]	60	70	80
Time synch. Accuracy better then [μ s]	1	0,5	0,3
Redundancy (recovery times) shorter then [ms]	10.000	100	0,25
Number of data objects more then [#of objects]	10.000	100.000	300.000

The international fieldbus – IEC 61784-2

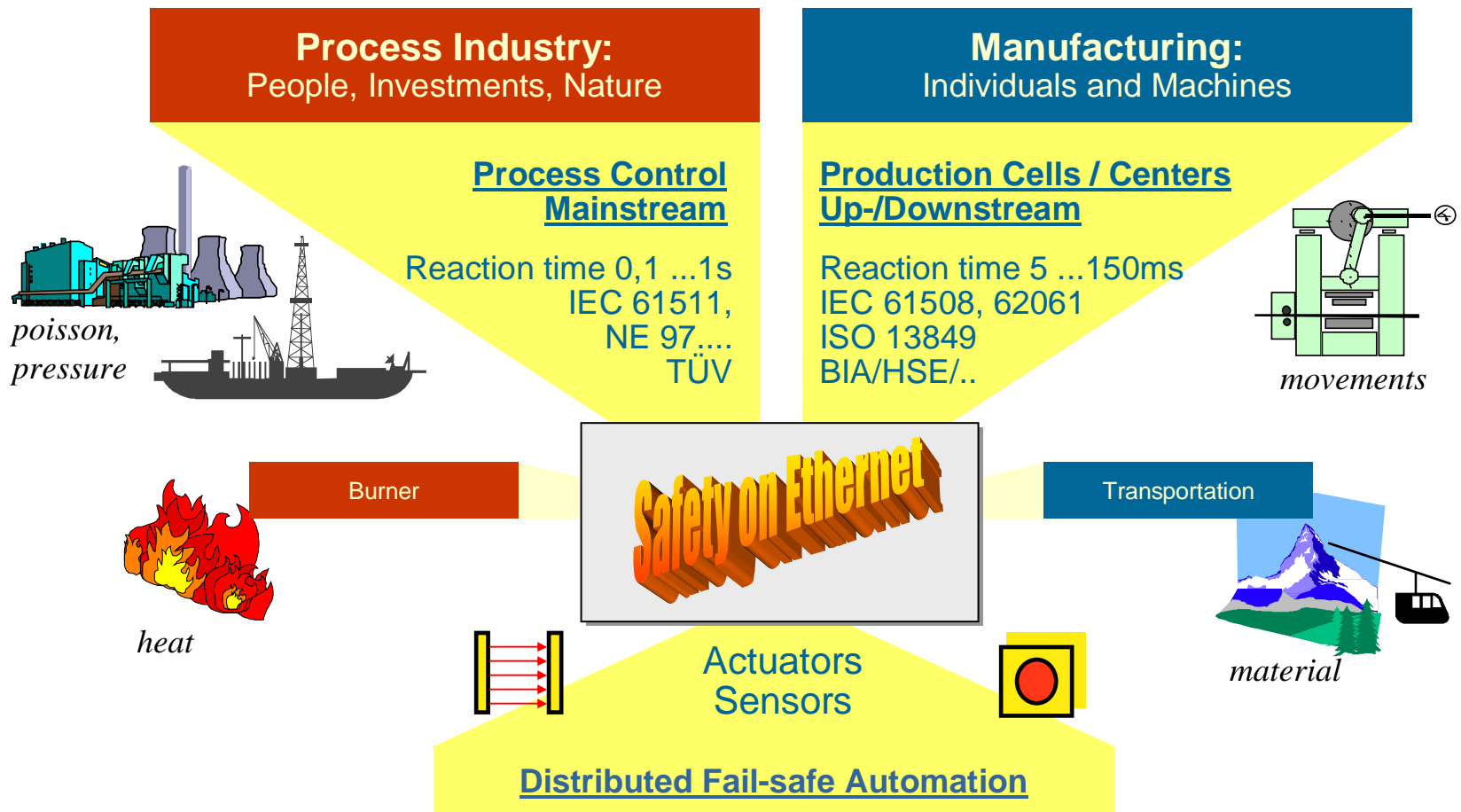
CPF2 (ControlNet™)	CP 2/2 EtherNet/IP
	CP 2/3 EtherNet/IP RTE?
CPF3 (PROFIBUS)	CP 3/3 PROFINET CBA
	CP 3/4 PROFINET I/O
	CP 3/5 PROFINET IRT
CPF4 (P-NET®)	CP 4/3 P-NET RTE ?
CPF6 (INTERBUS®)	CP 6/2 INTERBUS TCP/IP
	CP 6/4 INTERBUS RTE?
CPF10 (VNET/IP)	CP 10/4 VNET/IP
CPF11 (TCnet)	CP 11/4 TCnet
CPF12 (EtherCAT)	CP 12/4 EtherCAT
CPF13 (EPL)	CP 13/4 Ethernet Powerlink
CPF14 (EPA)	CP 14/4 EPA
CPF15 (Modbus-RTPS)	CP 15/4 Modbus-RTPS
CPF16 (SERCOS)	CP 16/4 SERCOS III

11 solutions will be referenced with several profiles each!

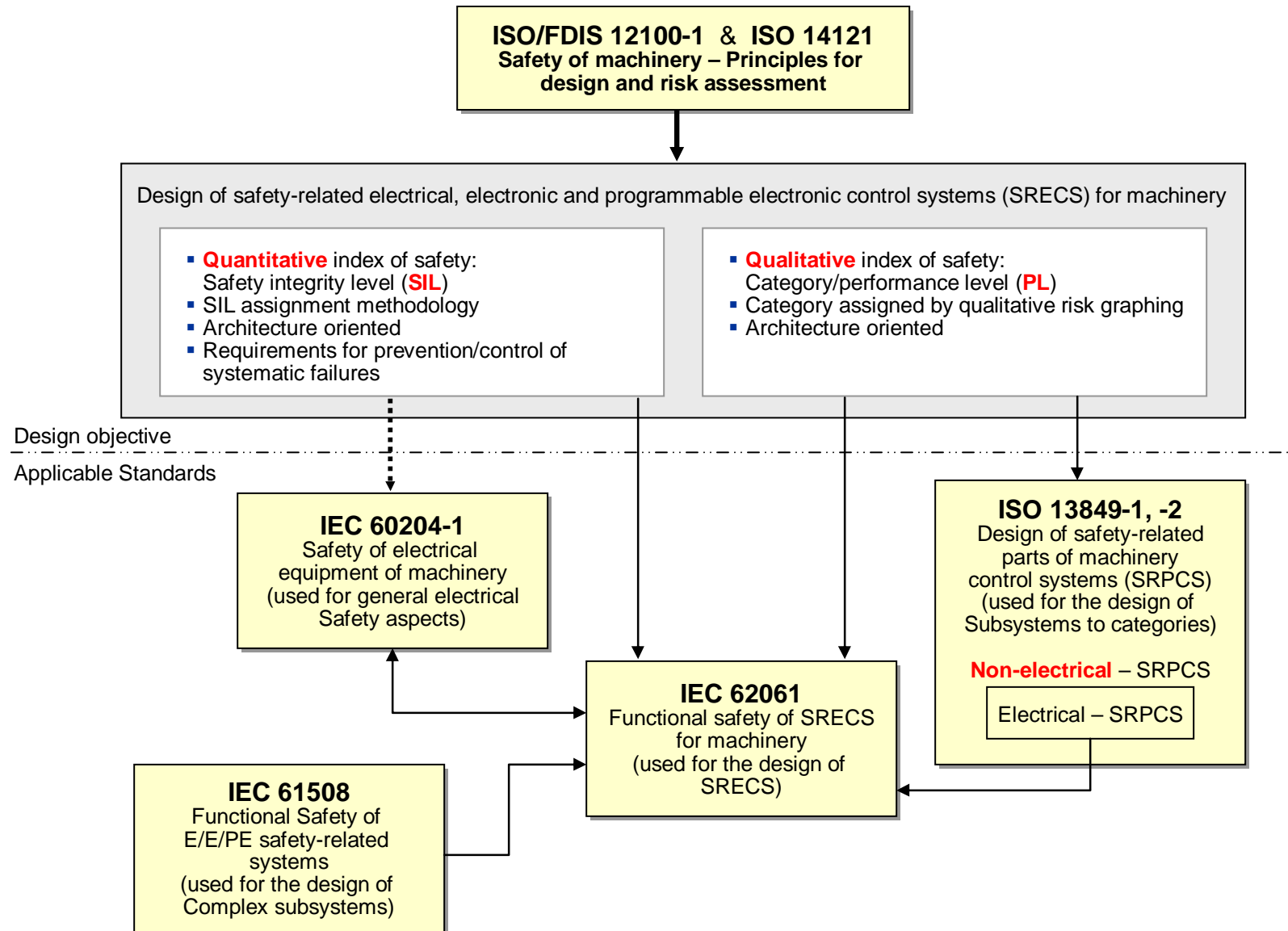
New structure of IEC65C for Industrial Ethernet



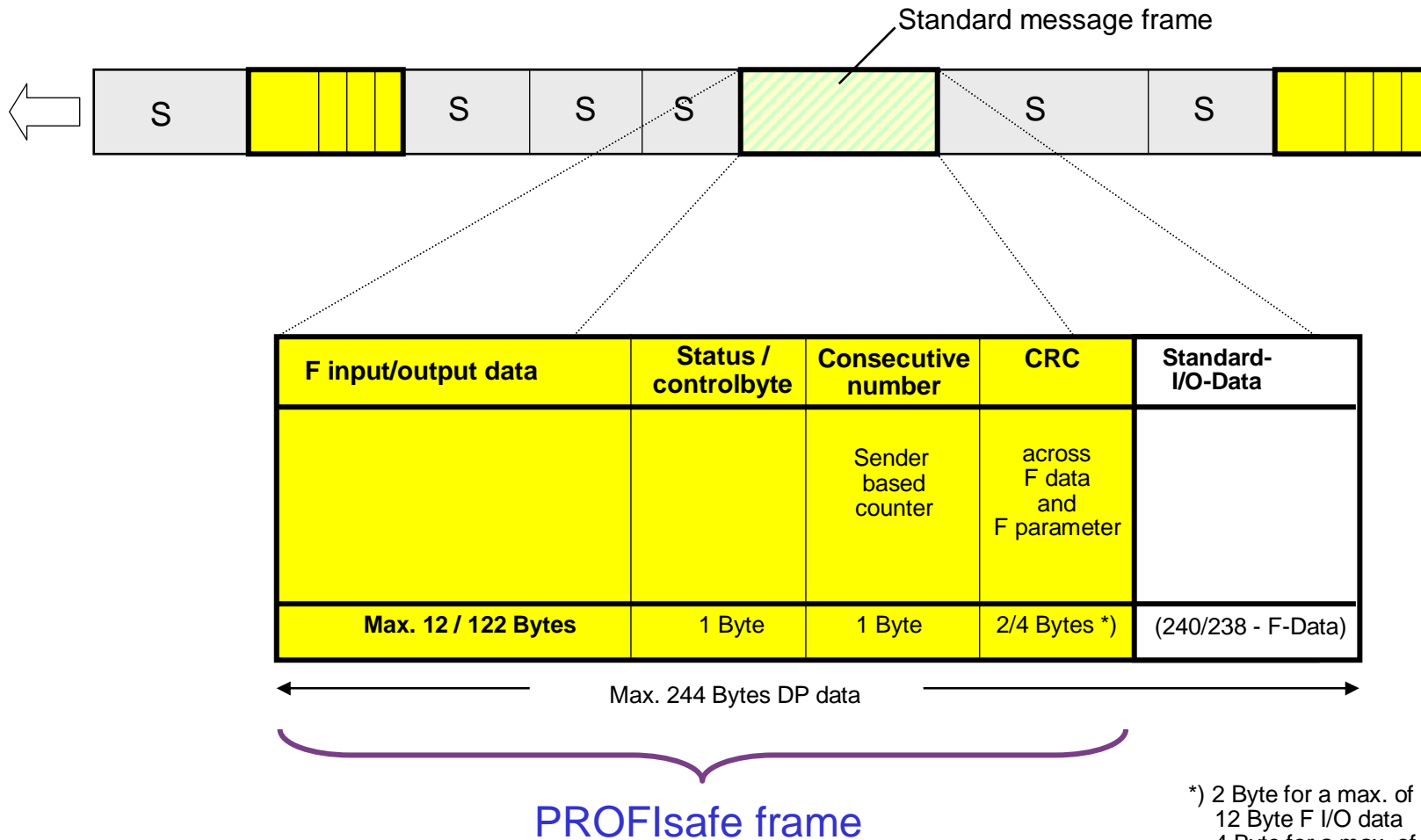
Industrial potential Risk Areas ...



Safety Standards for Machinery Applications



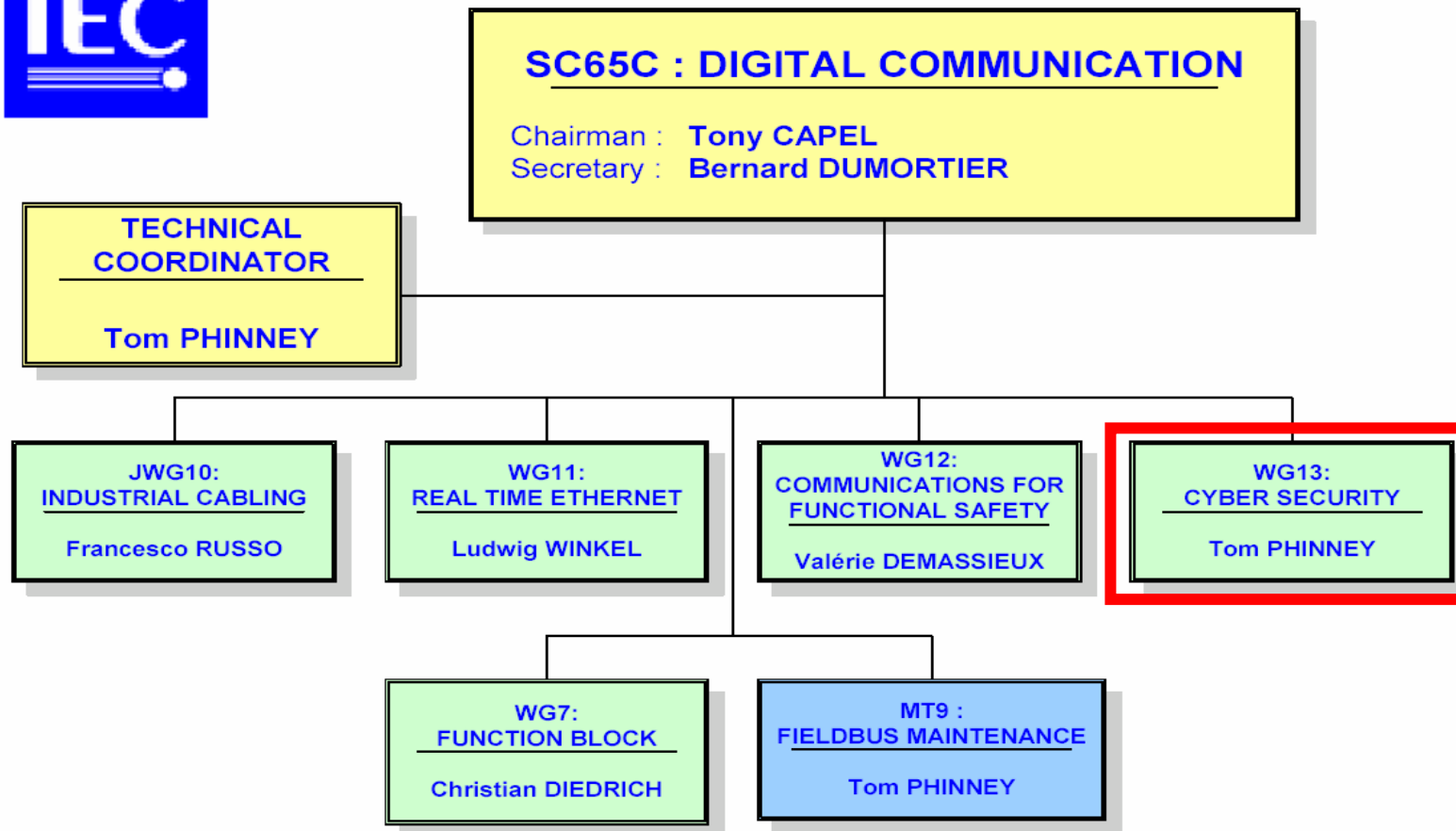
Example: PROFI-safe



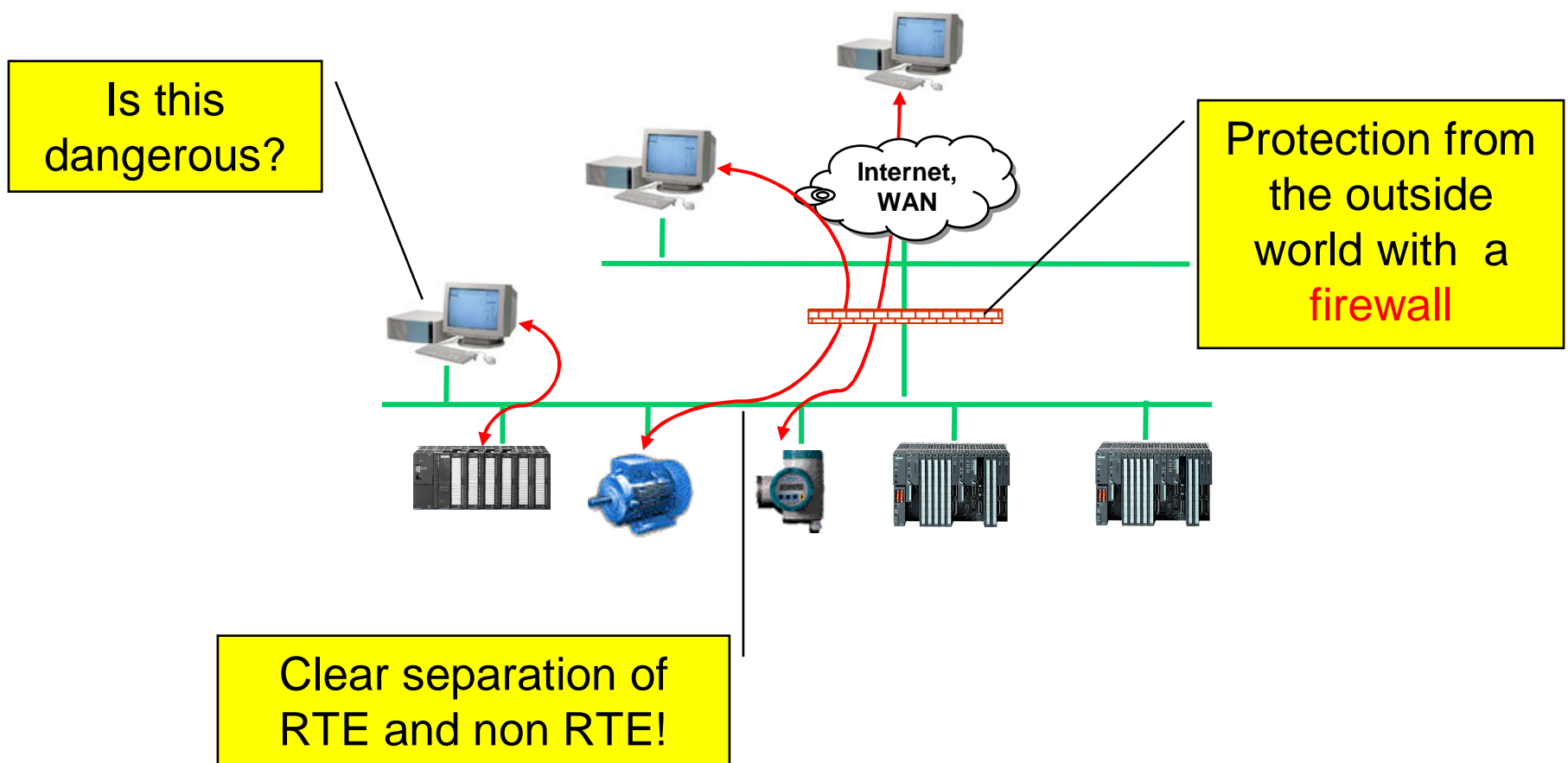
*) 2 Byte for a max. of 12 Byte F I/O data
4 Byte for a max. of 122 Byte F I/O data

There is no reason why these frame could not be transmitted over industrial Ethernet!

New structure of IEC65C for Industrial Ethernet



One Ethernet technology ?





Possible conclusions

- **The components and the installation rules for IT-Ethernet and Industrial-Ethernet are different**
- **To realize a RTE, we need different, more efficient protocols than TCP/IP or UDP/IP**
- **The network components like switches are different for Industrial Ethernet**
- **Additional security measures have to be taken**
 - ✓ **RTE offers more possibilities than a fieldbus**
 - ✓ **RTE is not cheaper than a fieldbus**
 - ✓ **The additional price makes only sense, if the additional features are really needed and used.**

Profiles are the key for future developments

- ⇒ Example of variable speed drives
- ⇒ Common generic interface to the PDS
- ⇒ How are industrial Ethernet solutions integrated?

Profiles:

